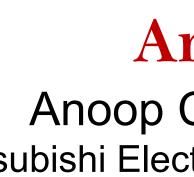


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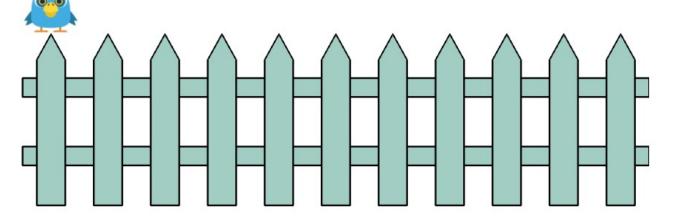


Massachusetts Institute of Technology



Problem:

Can a state-of-the-art (deep) machine learning model solve the simple puzzle below?



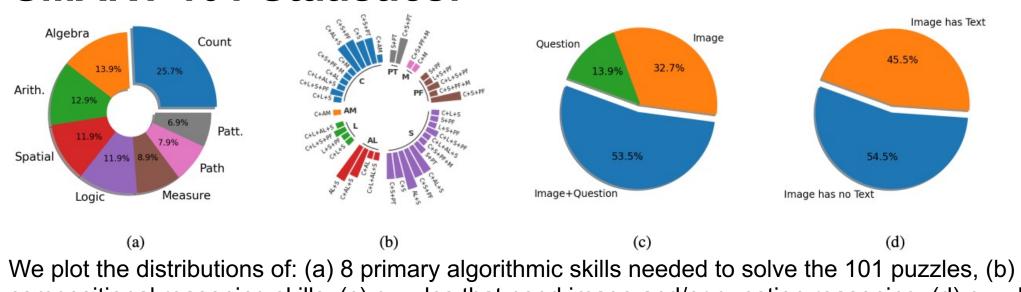
Question: Bird Bobbie jumps on a fence from the post on the left end to the other end. Each jump takes him 4 seconds. He makes 4 jumps ahead and then 1 jump back. Then he again makes 4 jumps ahead and 1 jump back, and so on. In how many seconds can Bobbie get from one end to the other end?

Answer Options: A: 64 B: 48 C: 56 D: 68 E: 72

Contributions:

- We introduce SMART: Simple Multi-modal Algorithmic **Reasoning Task** for evaluating the abstraction, deduction, and generalization abilities of neural networks in solving visuo-linguistic puzzles designed specifically for first/second grade children.
- To ensure the puzzles are solvable by kids, we take them from the Math Kangaroo (MK) Olympiad intended for second graders.
- (iii) We introduce the SMART-101 dataset built from 101 unique MK puzzles to evaluate the progress in multimodal artificial general intelligence.
- (iv) We propose **programmatic augmentation** to replicate each MK puzzle to arbitrary number of instances for training large machine learning models, so that the models learn the 'solution algorithm'.
- (v) We analyze the **generalization performances** of state-of-the-art vision and language pretrained models and show that they are not better than second grader performances (yet).

SMART-101 Statistics:

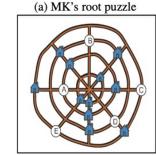


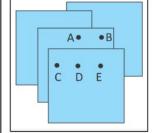
compositional reasoning skills, (c) puzzles that need image and/or question reasoning, (d) puzzles that need methods to read text within images (e.g., needing OCR abilities).

Are Deep Neural Networks SMARTer than Second Graders?

Anoop Cherian¹ Kuan-Chuan Peng¹ Suhas Lohit¹ Kevin Smith² Joshua B. Tenenbaum² ¹Mitsubishi Electric Research Labs (MERL), Cambridge, MA ²Massachusetts Institute of Technology (MIT), Cambridge MA {cherian, kpeng, slohit}@merl.com} {k2smith, jbt}@mit.edu

SMART Programmatic Puzzle Augmentations:





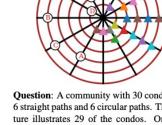
placed as shown. Michael wants to punch are kept as shown in the picture. Bridget of paper arranged as displayed. Daniel wants per are fixed as shown. Nathan needs to hole that goes through all four pieces. At have to to drill a hole that goes through all to punch a hole that passes through all seven punch a hole that passes through all eight which point should Michael punch the hole? eight pieces. What point should she drill the parts. At which location must Daniel punch pieces. What position must he punch the

ht pathways and 3 circular pathways.

nouse be built? Options: A, B, C. D. E

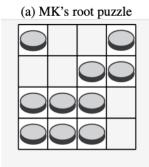


The image shows 5 of the houses. On each depicts 11 of the huts. On each straight lane raight road there are 3 houses. On each cir- straight pathway there are 2 houses. On each there are 3 huts. On each circular lane, there straight path there are 5 condos. On each alar road, there are also 3 houses. Where on circular pathway, there are also 2 houses, are also 3 huts. Which location on the map circular path, there are also 5 condos. Which Which location on the image should the 6th should the 12th hut be put? Options: A. B. place on the picture should the 30th cond

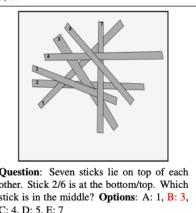


ture illustrates 29 of the condos. On eac be added? Options: A, B, C, D, E





be removed? **Options**: A: 0, B: 1, C: 2, D:

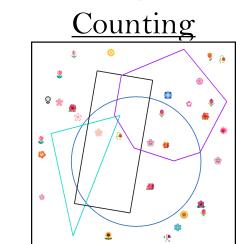


We use computer programs to replicate each puzzle; the arguments of these programs can be randomly sampled to produce various augmentations of the respective puzzle; e.g., change question, change appearances, etc. while keeping the underlying solution algorithm the same. We can control the difficulty of each puzzle as shown above using this method. Thus, when trained the expectation is that the model must learn the 'algorithm'

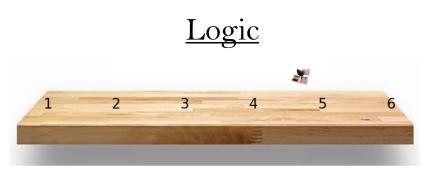
SMART Puzzle Categories:

Path Tracing

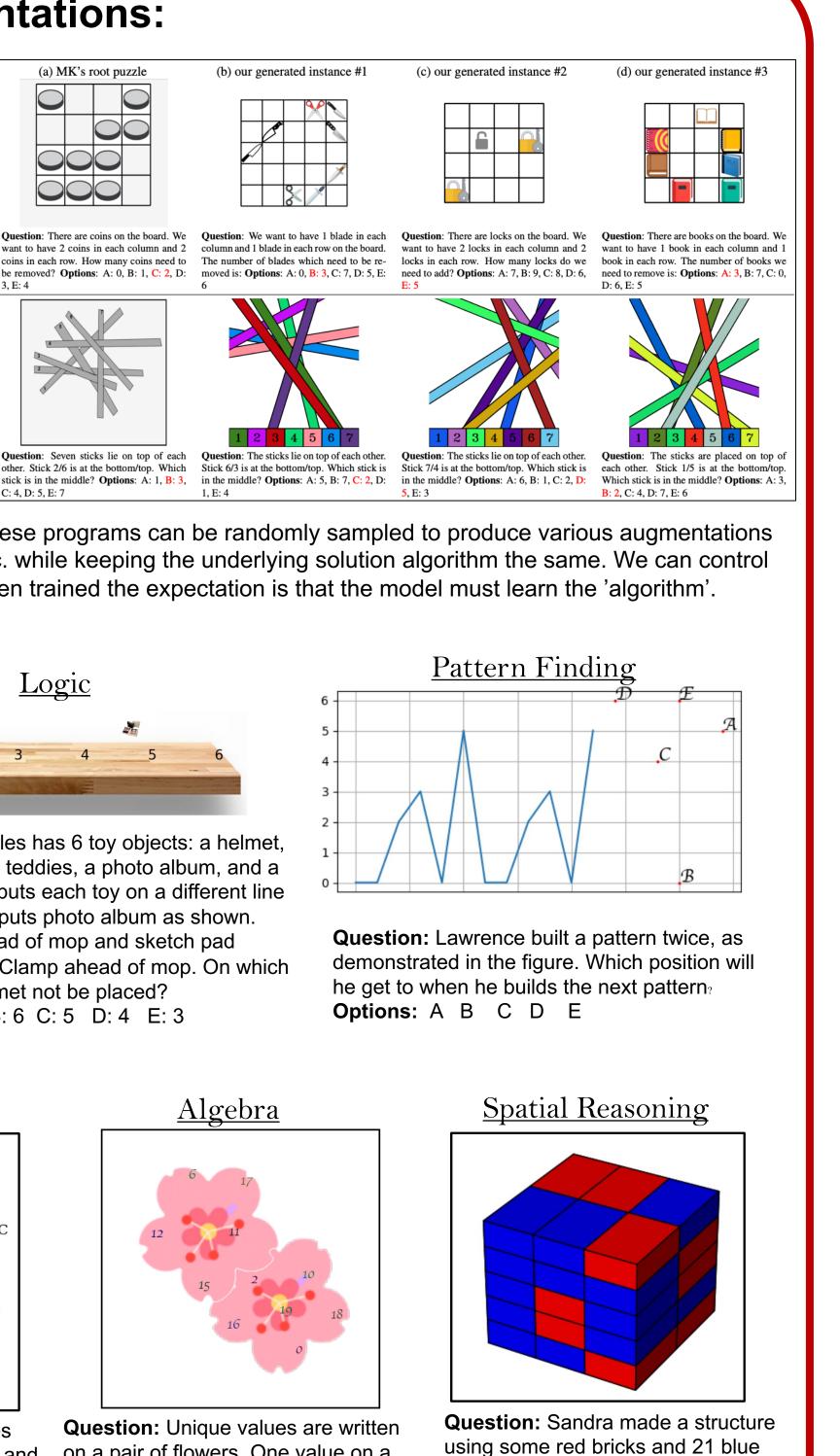
Question: Which object is linked to the hat? **Options:** A: flower B: disk C: book D: drink E: ball



Question: All the flowers which ar inside the circle but outside the triangle simultaneously are picked up. The number of flowers which are picked up is: **Options:** A: 7 B: 2 C: 6 D: 3 E: 5



Question: Charles has 6 toy objects: a helmet a clamp, a mop, teddies, a photo album, and a sketch pad. He puts each toy on a different line of the shelf. He puts photo album as shown. The helmet ahead of mop and sketch pad behind teddies. Clamp ahead of mop. On which line can the helmet not be placed? **Options:** A: 1 B: 6 C: 5 D: 4 E: 3

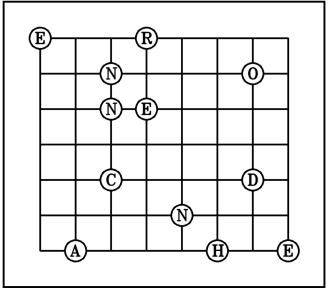


bricks. How many of these blue bricks

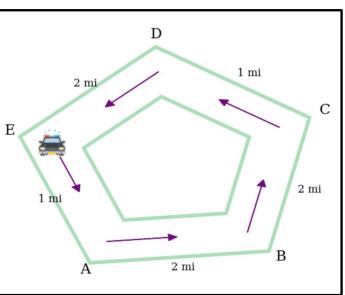
Options: A: 10 B: 11 C: 5. D: 1. E: 8

are not visible in the figure?

Measurement

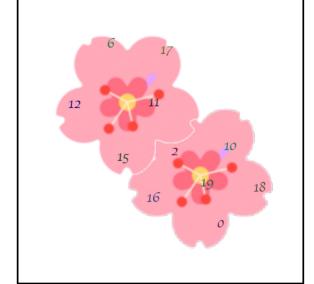


Question: We want to walk from N to E along the lines and pick up the letters NONADHERENCE in the correct order. The length of the shortest walk in units is (the length of each grid is 1 unit):? **Options:** A: 50 B: 44 C: 46 D: 47 E: 45 Arithmetic



Question: Albert the vehicle moves along the road. He starts at stop E and traverses the path of the arrows presented in the cartoon. The vehicle moves a total of 24 miles. Where does

<u>Algebra</u>



Question: Unique values are writte on a pair of flowers. One value on a flower is concealed. The sums of the values on the two flowers are identical. What is the concealed value? **Options:** A: 19 B: 8 C: 6 D: 11 E: 5

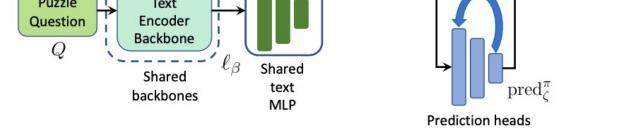
he end up? **Options:** A B C D E





Proiect Website

SMART Meta-Learning Reasoning Architecture: Puzzle-specific MLPs / Our architecture allows Options the SMART puzzles. We evaluate ViTs, ResNets, MAE, etc. for image and BERT/GPT/GloVe for Answer (



Experiments and Results:

Puzzle Category \rightarrow	Count	Arithmetic	Logic	Path Trace	Algebra	Measure	Spatial	Pattern Finding	Average
		Puzzle Spl	it (PS) – Ext	reme General	ization Expe	riments			
Avg. 2 nd Grader Performance	72.8	81.3	82.2	81.1	64.5	90.4	74.8	88.6	77.1
Greedy (baseline)	19.1/21.4	14.0/21.4	18.5/21.1	21.8/21.1	13.5/21.5	23.1/20.9	18.2/21.2	21.4/21.4	17.7/21.3
Uniform (baseline)	7.74/20.0	8.00/20.0	7.61/20.0	18.9/20.0	6.94/20.0	5.62/20.0	14.2/20.0	20.0/20.0	11.20/20
MAE + BERT	7.2/12.0	3.3/23.1	10.4/34.1	9.6/22.0	7.3/14.7	3.7/15.2	8.5/16.5	2.6/16.4	7.21/19.
SimSiam + BERT	6.4/18.4	4.8/20.9	7.7/41.4	2.5/22.2	4.2/25.3	7.9/20.5	11.8/22.2	0.2/17.2	6.41/23.
$Swin_T + BERT$	810.5/17.3	4.7/24.7	5.6/29.3	11.4/21.5	6.5/16.8	10.3/23.3	11.9/16.3	17.3/19.1	9.25/20.
ViT-16 + BERT	9.41/22.7	5.77/26.8	6.95/25.1	4.72/18.7	5.57/15.1	8.68/21.3	11.6/21.5	18.9/19.7	8.51/21.
CLIP	9.1/15.7	1.4/18.5	7.4/30.6	14.2/21.4	7.5/18.6	8.9/22.2	12.4/18.4	19.0/19.6	11.9/24.
FLAVA	8.3/20.2	4.0/22.2	8.1/31.3	9.5/20.3	3.1/22.2	19.0/32.0	9.7/18.1	20.9/21.2	7.21/19.
R50 + BERT (FT + Cls.)	10.9/18.3	6.96/15.8	12.8/20.8	19.6/19.7	7.95/15.1	16.9/26.7	13.4/17.7	0.0/21.2	11.7/18.
R50 + BERT (FT + Reg.)	12.0/22.8	5.08/21.3	4.24/16.2	18.4/18.4	4.89/22.2	15.1/25.9	11.9/17.9	19.0/19.0	8.21/19.
		Few	v-Shot Split (FS) Experime	ents, $m = 10$)			
R50 + BERT (Cls.)	17.3/28.0	11.2/25.8	18.0/37.6	19.2/19.2	7.9/21.9	14.8/31.2	18.7/25.8	17.8/17.8	15.2/25.
R50 + BERT (Reg.)	13.3/25.2	8.3/24.7	11.2/23.3	17.3/18.6	6.6/18.9	19.5/34.2	18.5/26.4	21.1/21.1	13.6/23.
		Instance S	Split (IS) – Si	upervised Lea	rning Experi	iments			
Greedy (baseline)	21.7/22.6	8.97/21.5	18.5/21.0	22.7/21.2	10.2/21.1	12.8/21.1	22.3/21.3	20.6/21.3	17.3/21.
Uniform (baseline)	9.41/20.0	3.65/20.0	7.91/20.0	11.1/20.0	5.01/20.0	3.63/20.0	15.5/20.0	16.7/20.0	8.41/20.
Swin-T + Emb.	23.1/35.1	33.7/41.0	20.3/28.8	16.7/18.6	17.7/29.5	26.3/34.3	24.5/29.1	17.5/26.5	22.5/30.
Swin-B + Emb.	22.0/34.0	29.4/36.5	17.7/26.1	16.7/17.0	17.1/30.2	25.0/34.2	26.2/30.7	21.5/29.6	21.6/29.
Cross-Transformer + Emb.	20.5/30.4	6.3/15.3	15.5/22.9	15.1/15.6	8.7/23.9	10.7/18.2	21.7/24.7	19.0/27.3	14.7/22.
ViT-16 + Emb.	25.6/36.4	39.7/47.1	21.2/30.8	15.5/16.3	20.1/33.8	39.4/40.8	29.0/33.0	20.3/29.6	25.9/33.
MAE + Emb.	25.4/36.7	34.2/43.2	21.6/31.5	16.4/16.7	20.0/33.3	32.0/39.7	28.2/32.9	18.6/26.6	24.5/33.
SimSiam + Emb.	44.9/56.1	35.1/43.5	45.7/50.8	25.0/26.6	23.4/35.1	64.7/73.5	55.0/57.2	42.8/49.1	39.5/47.
R18 + Emb.	44.0/54.0	8.8/19.8	41.1/47.6	24.5/26.7	13.7/26.5	30.9/40.2	43.3/45.5	29.5/34.8	29.4/37.
R50 + Emb.	46.6/57.8	38.0/45.9	43.2/50.1	24.6/26.4	23.3/35.1	56.9/67.4	57.9/58.6	44.8/51.0	39.8/47.
R50 + GloVe	46.0/56.3	39.2/48.5	53.9/56.4	26.7/28.9	21.5/32.4	58.9/68.5	48.5/50.4	43.3/47.8	40.0/47.
R50 + GPT2	47.0/57.9	44.8/53.1	55.1/58.6	26.1/28.4	27.2/39.3	61.0/71.3	49.0/50.2	42.5/48.4	42.1/49.
R50 + BERT	48.5/59.3	46.1/54.9	56.7/60.2	26.5/28.4	28.5/39.7	65.6/75.4	44.3/46.2	39.9/45.3	42.8/50
CLIP	41.3/52.9	18.2/29.3	33.3/41.1	19.8/21.9	12.9/24.9	27.8/42.8	32.2/36.2	29.9/36.1	27.3/36.
FLAVA	47.7/58.1	20.2/29.7	41.4/47.1	25.4/27.1	19.6/31.2	30.5/41.9	33.2/35.7	38.3/44.2	32.3/40.
		Answer Sp	lit (AS) – An	swer General	ization Expe	riments			
R50 + BERT (FT + Cls.)	0.1/23.8	1.5/13.2	0.0/16.8	0.0/1.6	0.4/17.3	0.0/21.1	0.0/6.0	0.0/15.0	0.19/10.
R50 + BERT (FT + Reg.)	12.0/28.4	10.4/25.7	19.6/30.8	9.5/10.6	3.64/18.3	9.42/28.6	14.1/21.1	25.5/30.9	16.3/23.

puzzle ID 7 9 30 38 47 71 88 Category NA NA NA NA 4.65 NA NA 98.0 14.0 100.0 64.6 93.7 56.7 21.3 55.7 IS split

Comparisons on large language models using a text subset of SMART 101.

evaluating varied image and backbone networks for solving

language backbones. We also compare to vision-andlanguage models such as CLIP & FLAVA.

90 91 93 mean AL L M M NA NA NA 60.4 10.0 20.0 30.0 12.7 30.0 60.0 90.0 36.4 10.0 20.0 30.0 26.4 0.0 0.0 100.0 15.5
NA NA NA NA 60.4 10.0 20.0 30.0 12.7 30.0 60.0 90.0 36.4 10.0 20.0 30.0 26.4 0.0 0.0 100.0 15.5
10.020.030.012.730.060.090.036.410.020.030.026.40.00.0100.015.5
30.060.090.036.410.020.030.026.40.00.0100.015.5
10.0 20.0 30.0 26.4 0.0 0.0 100.0 15.5
0.0 0.0 100.0 15.5
0.0 0.0 20.0 25.5
0.0 0.0 30.0 35.5
NA 25.5 NA 15.1
51.3 26.3 34.0 55.9